

# Multiscale Gyrokinetic Analysis in the Tokamak Pedestal

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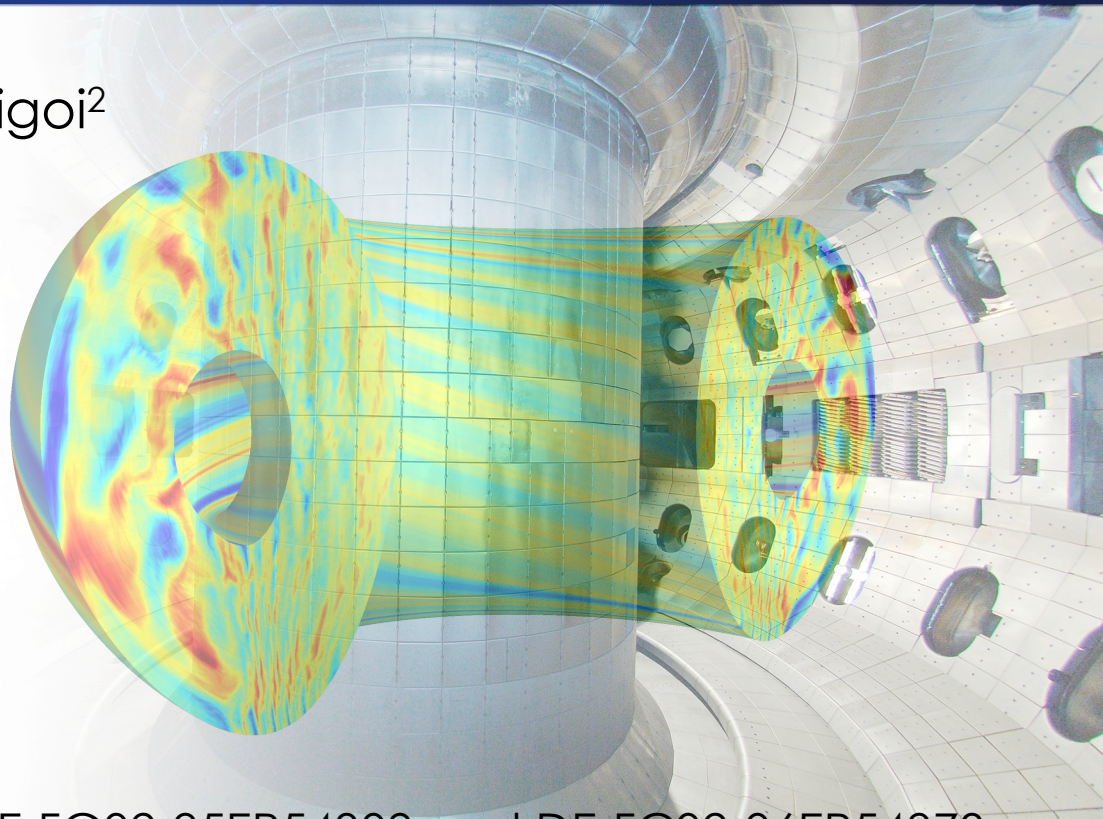
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Supercomputing Center

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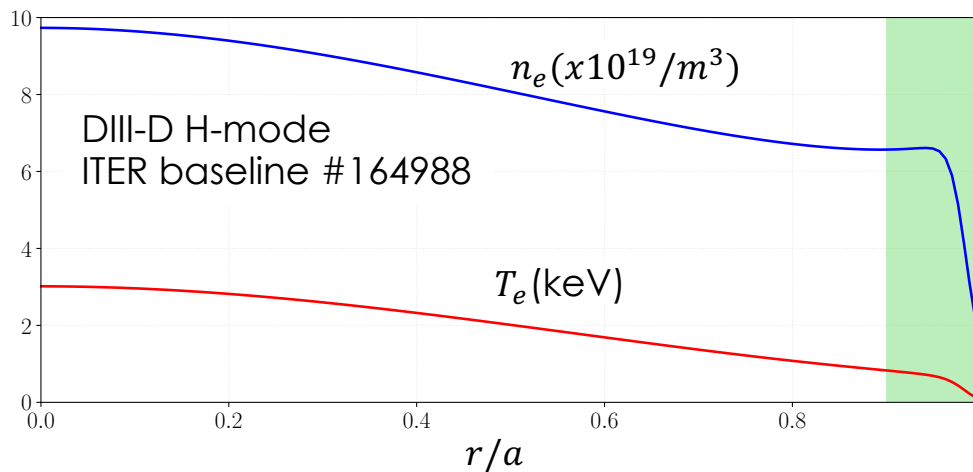
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# Understanding transport in the H-mode pedestal can help to develop operating regimes for optimal confinement and fusion performance.

- The most promising operating scenario for achieving fusion in tokamaks is **H-mode confinement regime**.
- H-mode is characterized by the formation of edge transport
- Region of reduced transport leads to steeper gradients in density and temperature → “**pedestal**” structure at the edge of the plasma
- Pedestal plays a key role in **determining global energy confinement**.

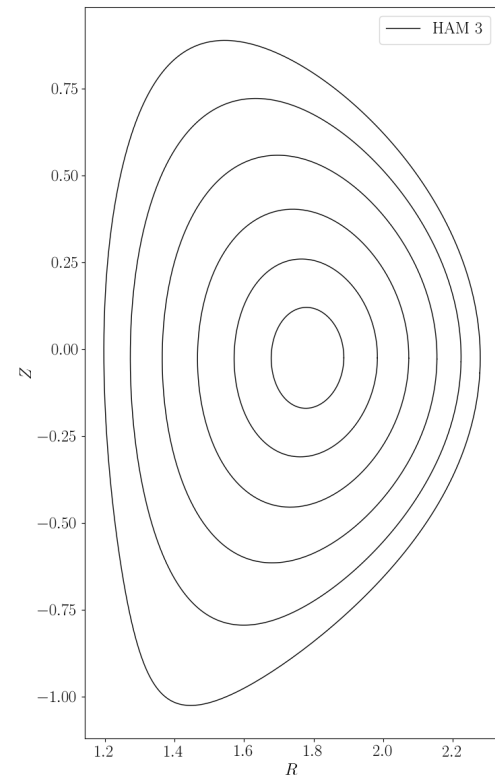
**Turbulent transport in pedestal is less well understood than in the core.**



# While ion-scale turbulence in the core has been modeled extensively, multiscale pedestal simulations are far more challenging.

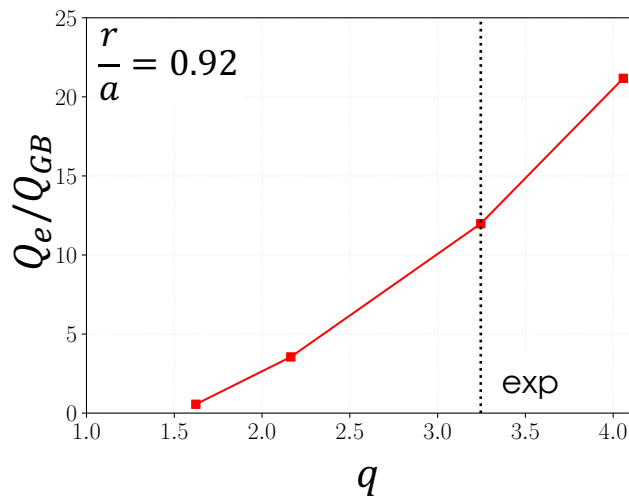
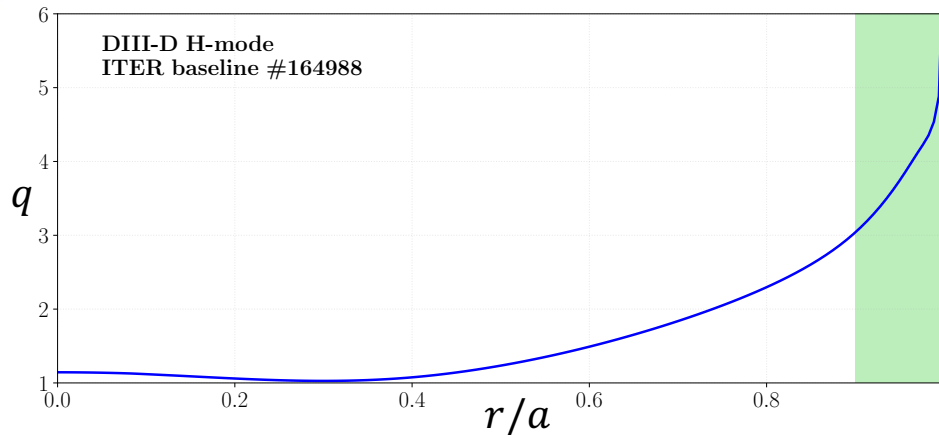
- **Strongly shaped edge geometry**
  - Need 2-6X increase in resolution in parallel (field-line) direction  $\theta$

DIII-D H-mode ITER Baseline #164988



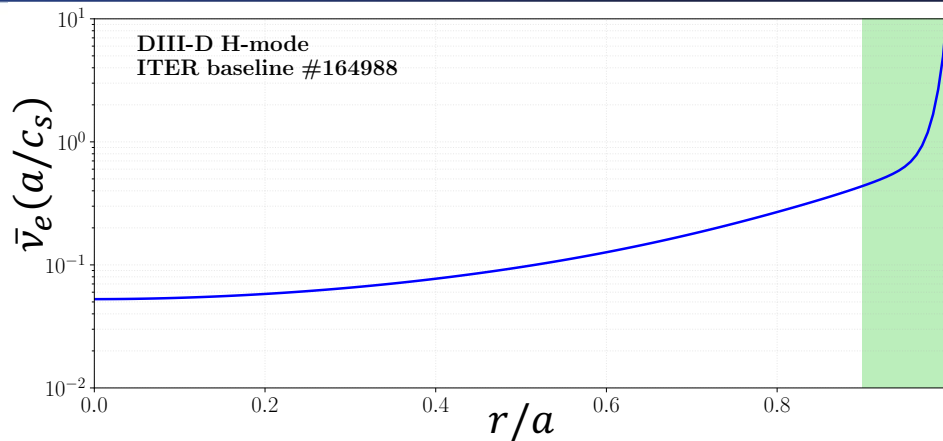
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- **Weaker pitch of confining magnetic field (large safety factor  $q$ )**
  - Need large radial resolution



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  - Need large radial resolution
- **Large collisionality**
  - Need advanced collision models

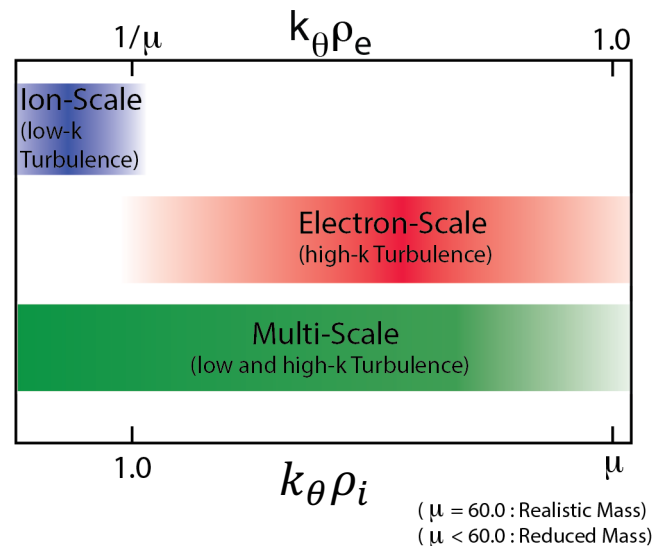


Standard e pitch angle scattering  
+ energy diffusion  
+ conservation ( $n, v, E$ )  
+ inter-species (**multiscale in velocity space**)

# While ion-scale turbulence in the core has been modeled extensively, multiscale pedestal simulations are far more challenging.

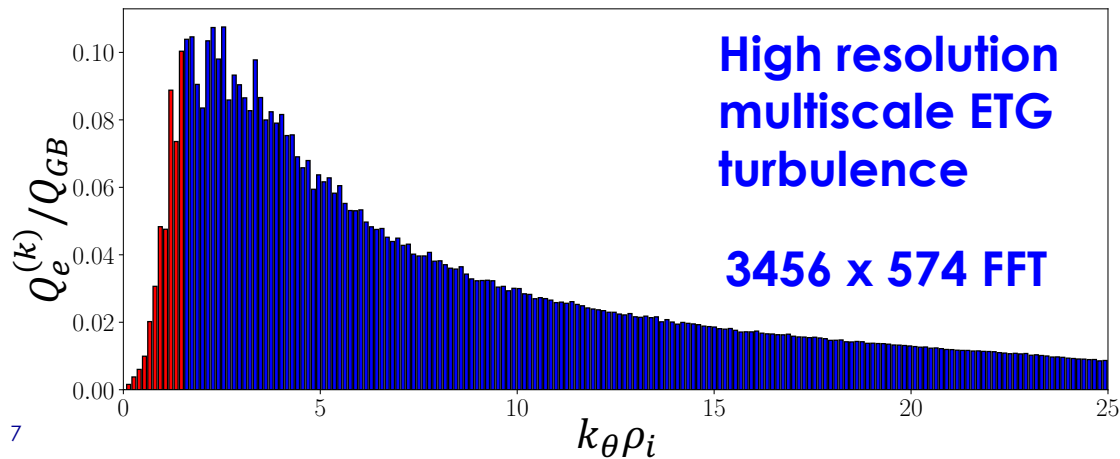
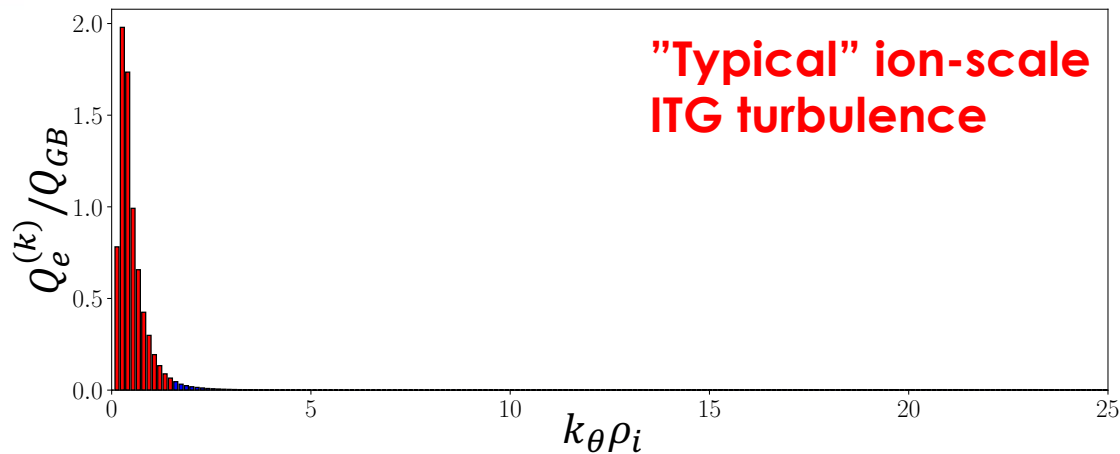
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- Large collisionality
  - Need advanced collision models
- **Large gradients drive multiple instab. across broad range of spatial scales**
  - **Ion-scales** ( $k_{\theta}\rho_i \lesssim 1$ ): ES modes (ITG, TEM), EM modes (MTM)
  - **Electron-scales** ( $k_{\theta}\rho_e \sim 1$ ): ETG

Scales Simulated in Different Simulation Types



**Electron heat transport** will play a dominant role in reactors  
→ **Multiscale resolution needed**

# While ion-scale turbulence in the core has been modeled extensively, multiscale pedestal simulations are far more challenging.



Requires **leadership-scale computing resources** and **highly optimized solvers**.

# CGYRO: A multiscale-optimized gyrokinetic turbulence solver

- Solves the 5D (3 spatial+2 velocity)  $\delta f$  gyrokinetic-Poisson-Ampere equations using **Eulerian approach**
- Motivations are **accurate collisions** in H-mode pedestal and and to provide efficient nonlinear, electromagnetic **multiscale simulations**.
  - Complex nonlinear cross-scaling coupling requires extremely fine mesh in real space
    - **Specialized numerical schemes** are needed to prevent severe bottlenecks related to:
      - gyroaveraging
      - Maxwell field solve
      - ExB nonlinearity



# CGYRO implements highly efficient spectral/pseudospectral numerical schemes optimized for multiscale simulations.

<b>x</b>	<b>Radial</b>	<b>spectral</b>
<b>y</b>	<b>Binormal</b>	<b>spectral</b>
<b><math>\theta</math></b>	<b>Poloidal</b>	<b>Finite diff</b>

$$H_a(\mathbf{x}, \mathbf{y}, \theta, \xi, \mathbf{v})$$

<b><math>\xi</math></b>	<b>Pitch angle</b>	<b>pseudospectral</b>
<b>v</b>	<b>Velocity</b>	<b>psuedospectral</b>

- **Fully spectral in  $(x, \alpha)$**  provides maximal multiscale efficiency
  - Ensures collision operator is algebraic in space
  - Allows for most efficient evaluation of gyroaverages
  - Evaluation of nonlinear term on GPUs (cuFFT) ensures maximum performance and scalability
- **Pseudospectral in  $(\xi, v)$**  provides optimal accuracy of collisions

Unlike most gyrokinetic codes, CGYRO uses velocity-space coordinates optimized for the collisional problem.

**GYRO & GS2 use  $(\lambda, \varepsilon)$  coordinates**

$$\lambda = \frac{v_{\perp}^2}{v^2 B} \quad \varepsilon = \frac{m_a v^2}{2T_a}$$

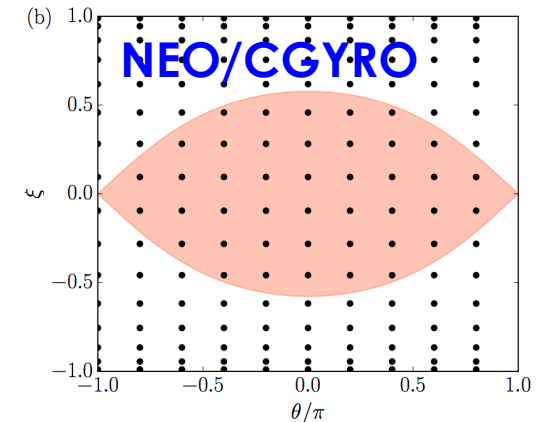
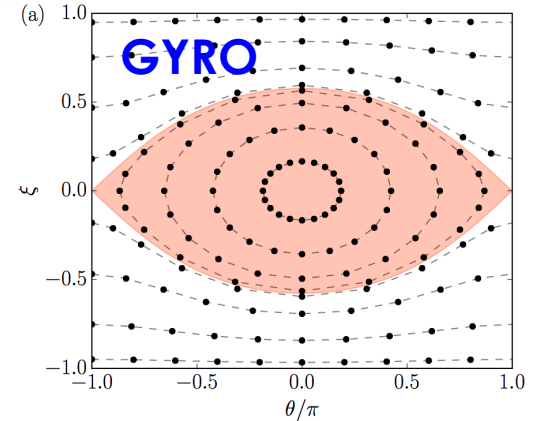
**Advantage:**

No need for derivatives across trapped/passing boundary since  $\theta$  discretization is aligned with particle orbits

**Disadvantage:**

Difficult to evaluate collision operator due to irregular grid in  $(\xi, \theta)$   $\mathcal{L} = \frac{1}{2} \frac{\partial}{\partial \xi} (1 - \xi^2) \frac{\partial}{\partial \xi}$

**NEO has instead had great success with  $(\xi, v)$  coordinates**, implementing spectrally-accurate collision operators.



# CGYRO has the first pseudospectral implementation of the collision operator in a gyrokinetic code.

- Legendre polynomials in  $\xi$
- Nonstandard orthogonal polynomials in  $v$

$$\mathcal{L} = \frac{1}{2} \frac{\partial}{\partial \xi} (1 - \xi^2) \frac{\partial}{\partial \xi}$$

$$\xi = v_{\parallel}/v$$

$$u_a = v/\sqrt{2v_{ta}}$$

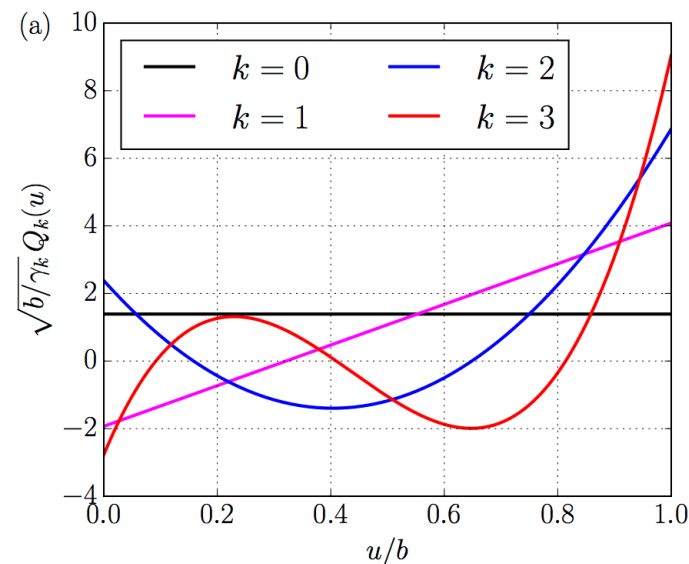
- Accurate for energy integration and differentiation
- Appropriate for semi-infinite energy domain

$$\int_0^b du e^{-u^2} Q_k(u) Q_l(u) = \gamma_k \delta_{kl}$$

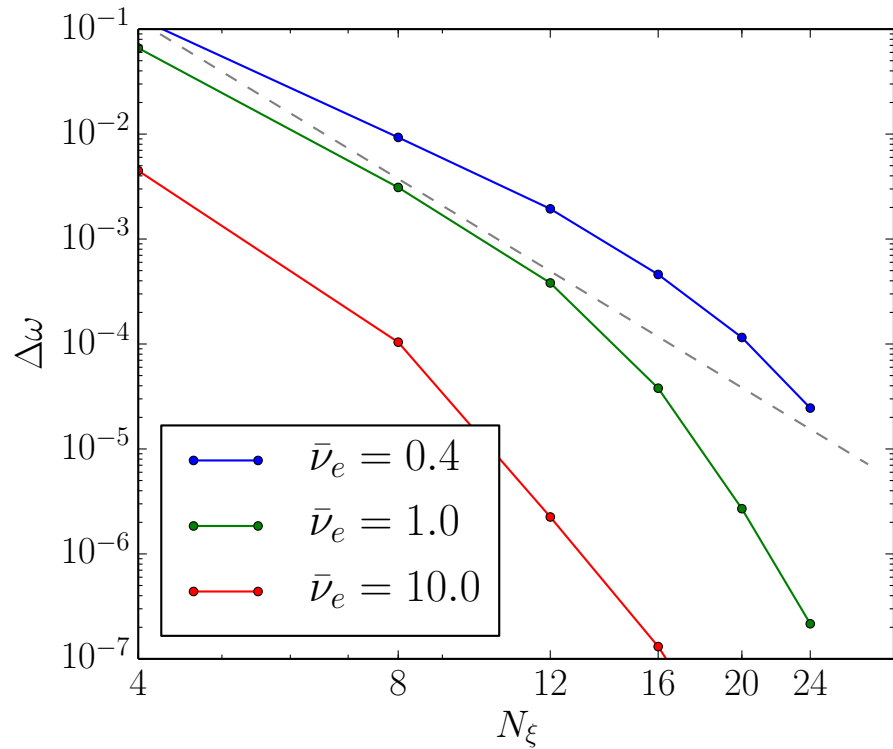
$$u \in [0, b]$$

$b \rightarrow 0$ : shifted monic Legendre

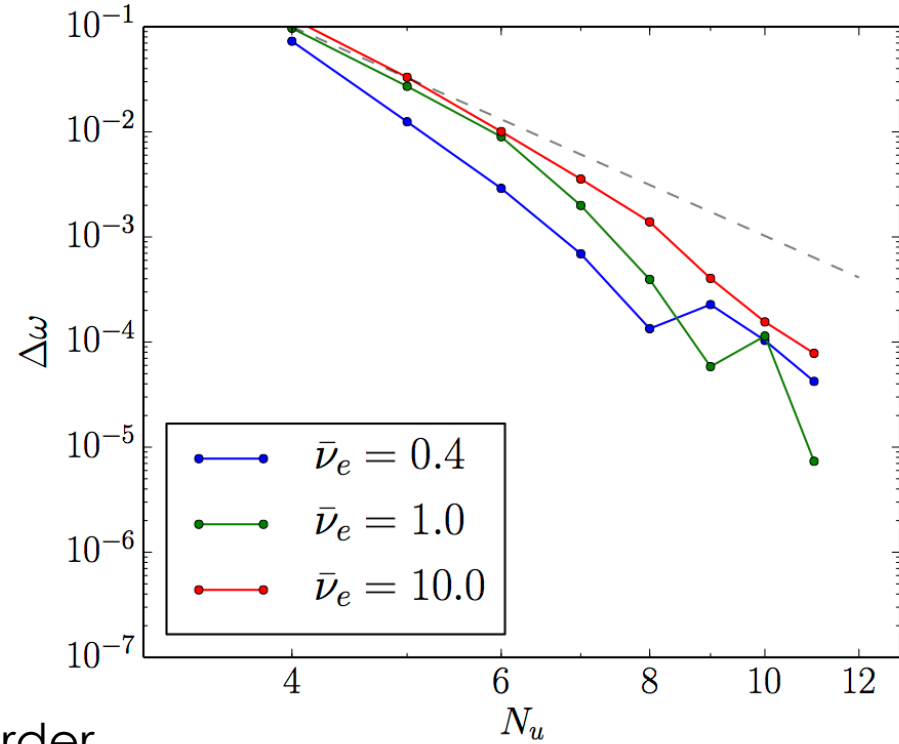
$b \rightarrow \infty$ : half-range Hermite



# Spectral convergence in $(\xi, \nu)$ velocity space is observed.



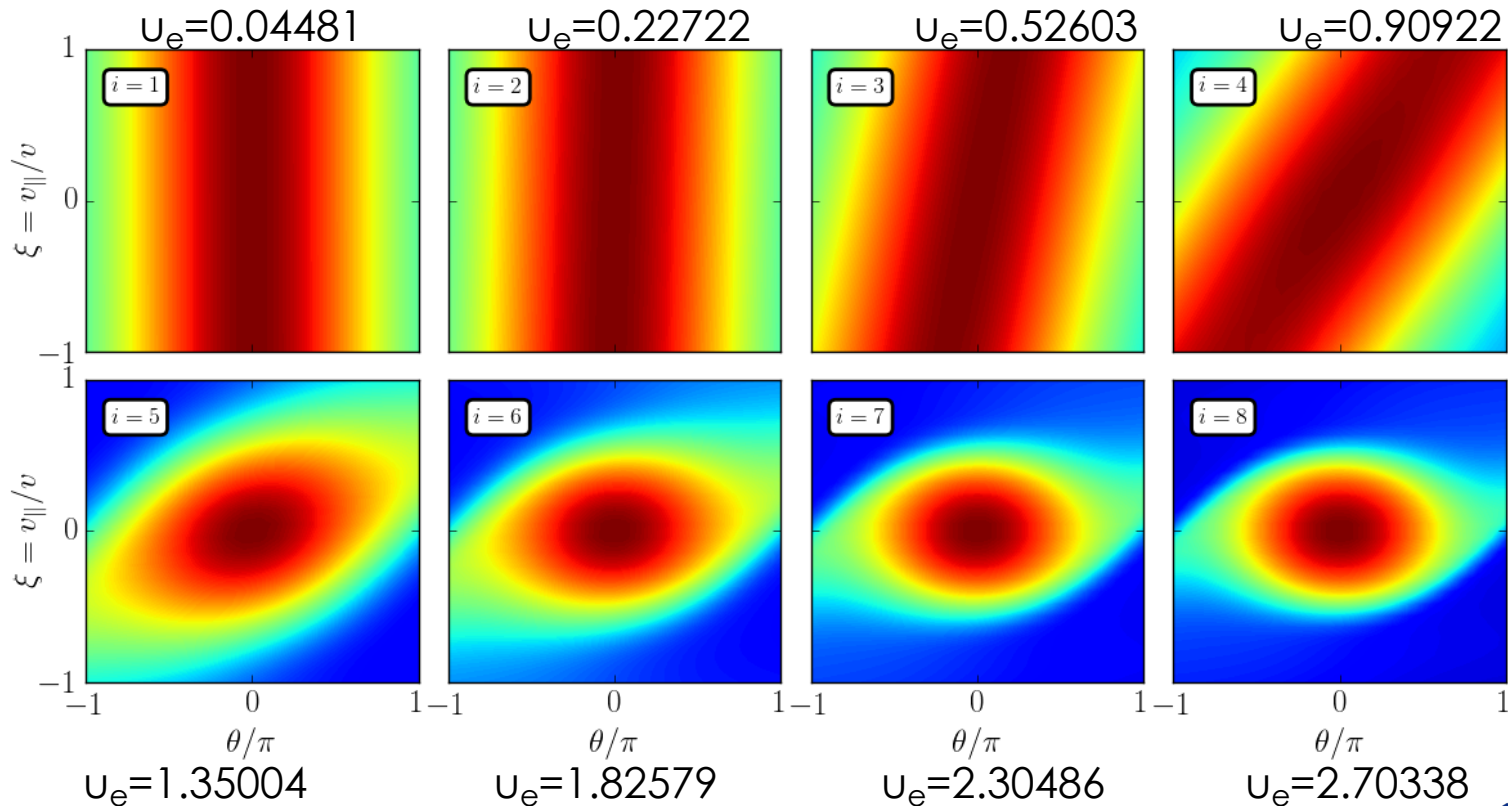
--- 4<sup>th</sup> order



# The GKE exhibits highly-collisional behavior at the lowest energies, transitioning to collisionless behavior at high energies.

$|H_e|$  at various energy meshpoints

$\bar{v}_e = 1.0$



# CGYRO operator splitting for time integration

$$\frac{\partial h_a}{\partial \tau} + A(H_a, \Psi_a) + B(H_a, \Psi_a) = 0$$

- **Nonlinear, Collisionless step:**
  - **Operates primarily in space** (distributed in velocity dimensions)
    - Spectral in x and y; finite difference in  $\theta$
  - Nonlinearity via **2D FFT with dealiasing (well-suited to GPUs → cuFFT)**
  - Explicit in time: **Adaptive embedded RK5(4)**
    - Time step restriction set by fastest Alfvén wave
    - Efficient for nonlinear multiscale (large number of radial & binormal wavenumbers)
    - Adaptive algorithm gives faster solution for systems with impulse and oscillatory behavior

# In the field line direction, a novel 5<sup>th</sup> order conservative algorithms is used to permit high-accuracy electromagnetic simulation.

- Focus on schemes suitable for **explicit advection**

$$\boxed{\frac{\partial h_a}{\partial \tau} + \hat{v}_{\parallel} \frac{\partial H_a}{\partial \theta}}$$

$$H_a = h_a - G_{0a} \tilde{v}_{\parallel} \delta A_{\parallel} + G_{0a} \delta \phi$$

- Implement a **5<sup>th</sup> order upwind scheme**:

$$\boxed{\frac{\partial (h_a)_j}{\partial \tau} + \hat{v}_{\parallel} \mathbf{D}^{(6)} (H_a)_j + |\hat{v}_{\parallel}| \mathbf{S}^{(6)} (g_a)_j}$$

$$g_a = h_a - G_{0a} \tilde{v}_{\parallel} \delta A_{\parallel}$$

**6<sup>th</sup>-order finite difference**  
(7-pt derivative)

**6<sup>th</sup>-order filter**  
(7-pt smoother)

**$\mathbf{S}^{(6)} \sim (\Delta \theta)^5$ : Continuum limit obtained as num gridpts increases**

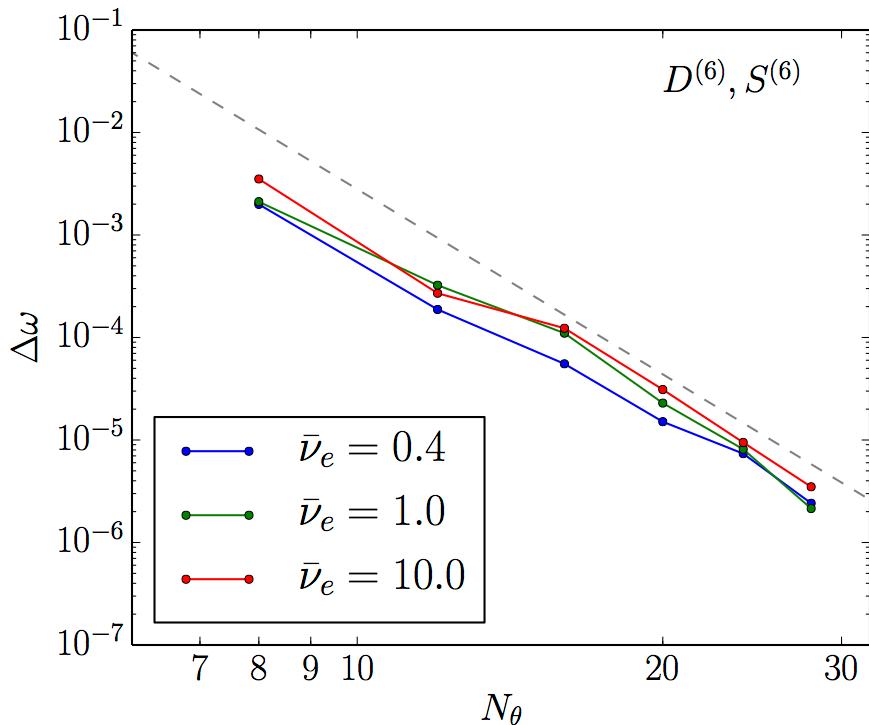
# The conservative upwind scheme yields accurate discretization in the long-wavelength, high beta limit and for high-k ETG modes.

$$\frac{\partial (h_a)_j}{\partial \tau} + \hat{v}_{\parallel} D^{(6)} (H_a)_j + S^{(6)} [|\hat{v}_{\parallel}| (g_a)_j - \langle (g_a)_j \rangle]$$



## Density conservation

- **Dissipation** causes inaccuracy due to violation of number conservation
- **Project out the gyrocenter density distribution caused by the dissipation**
- Method **conserves gyrocenter number** with respect to the numerical dissipation





# CGYRO operator splitting for time integration

$$\frac{\partial h_a}{\partial \tau} + A(H_a, \Psi_a) + B(H_a, \Psi_a) = 0$$

- **Collisional + trapping step:**

- **Operates in velocity space** (distributed in spatial dimensions)
- Implicit in time: **2nd order CN**
  - Required for stability due to scaling of  $v_e$  with inverse powers of  $v$
  - Matrix is large and well-suited to execution on GPUs

$$\begin{bmatrix} H_1^+ \\ H_2^+ \\ \vdots \\ H_{N_a}^+ \end{bmatrix} = \mathbb{M} \begin{bmatrix} H_1^- \\ H_2^- \\ \vdots \\ H_{N_a}^- \end{bmatrix}$$

$$\text{Rank}(\mathbb{M}) = N_\xi N_v N_a$$

# CGYRO uses a spatial discretization & array distribution scheme that targets scalability on next-generation HPC systems

- Operates on 5+1 dimensional grid
- Several steps in the simulation loop, where each step
  - Can cleanly partition the problem in at least one dimension
    - But no one dimension in common between all of them
  - All dimensions are compute-parallel
    - But some dimensions may rely on neighbor data from previous step

**Easy to split among several CPU/GPU cores and nodes**

**Requires frequent transpose ops** (i.e. MPI\_ALLtoALL)  
→ Communication heavy

# CGYRO uses a spatial discretization & array distribution scheme that targets scalability on next-generation HPC systems

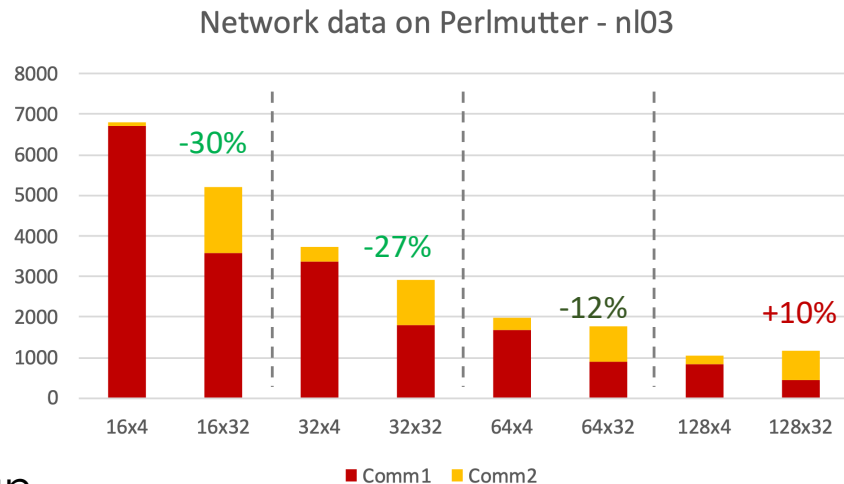
Communication happens on **2 orthogonal communicators**

Kernel	Data dependence	Dominant operation	Communication
Collisionless	$k_x^0, \theta$ $[k_y]_1, [\xi, v, a]_2$	Loop (linear)	MPI_ALLREDUCE
Nonlinear	$k_x^0, k_y$ $[\theta, [\xi, v, a]_2]_1$	FFT	MPI_ALLTOALL
Collisional	$\xi, v, a$ $[k_y]_1, [k_x^0, \theta]_2$	Matrix-vec multiply	MPI_ALLTOALL

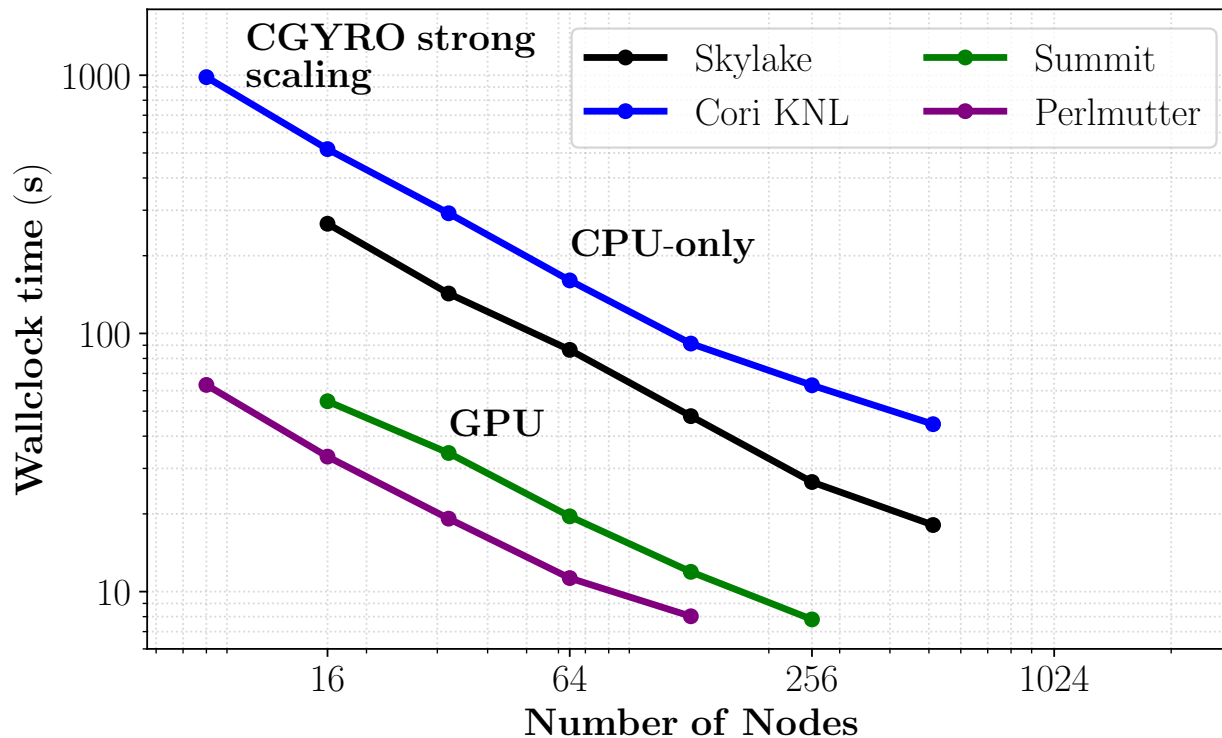
- **All CGYRO kernels are ported to GPUs** using OpenACC and cuFFT
- **Critical use of GPUDirect MPI** minimizes cost of memory movement
  - Gives 30-40% reduction in comm timing on OLCF Summit
  - **Optimal for Frontier**

# CGYRO uses a spatial discretization & array distribution scheme that targets scalability on next-generation HPC systems

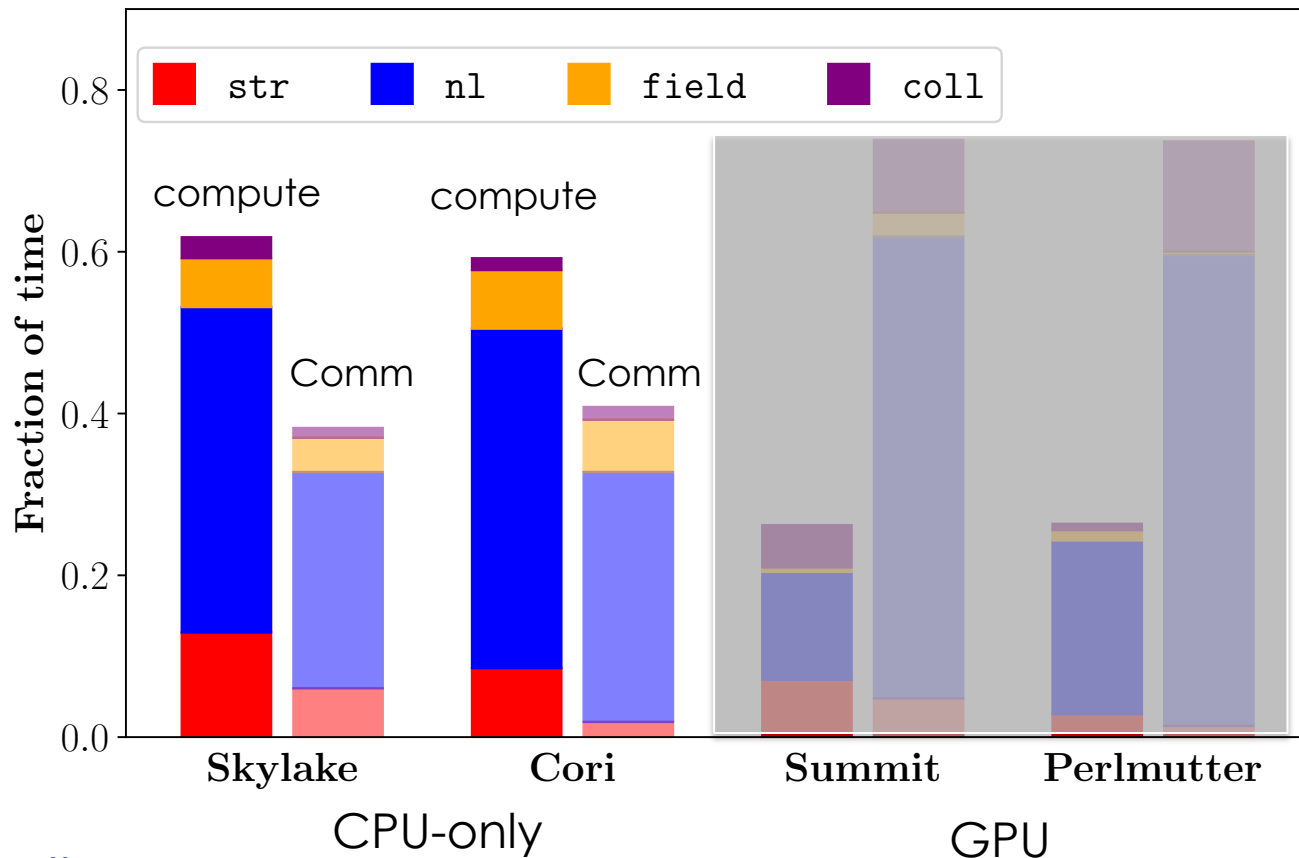
- **For small to medium simulations:**
  - Comm1 is typically more "chatty"
  - Keep most of data inside the node to reduce network traffic
  - But increasing #MPI, increases data comm of Comm2
- **For multiscale:**
  - When #MPI is multiple of #species, can **exchange only per-species data** and comm2 data volume cut by #species
  - **Smarter, adaptive time advance** reduces both compute time and data volume



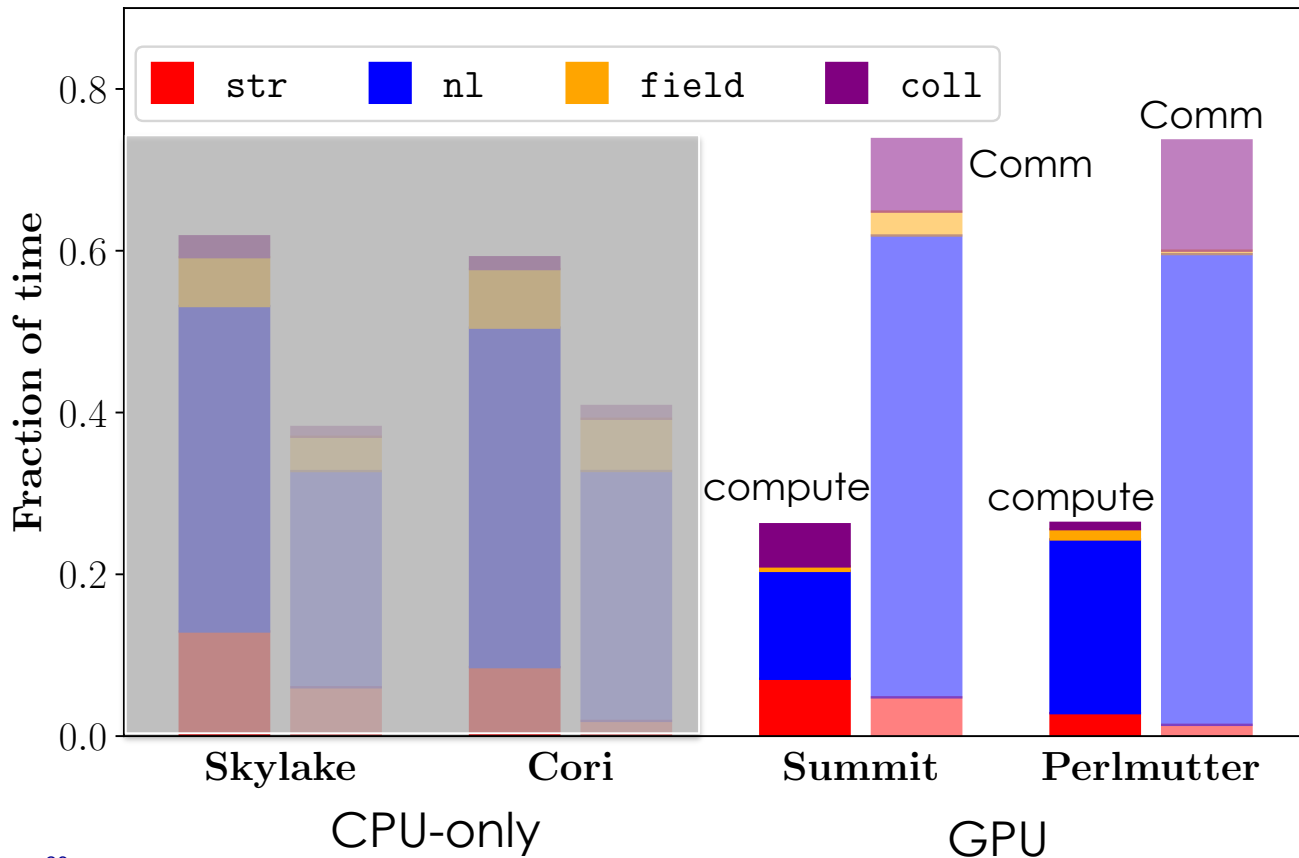
# CGYRO strong scaling shows excellent performance on GPU systems on both a per node and maximum performance basis.



# On CPU systems, compute time is dominated by nonlinear FFT and cost of communication:compute ratio is smaller.



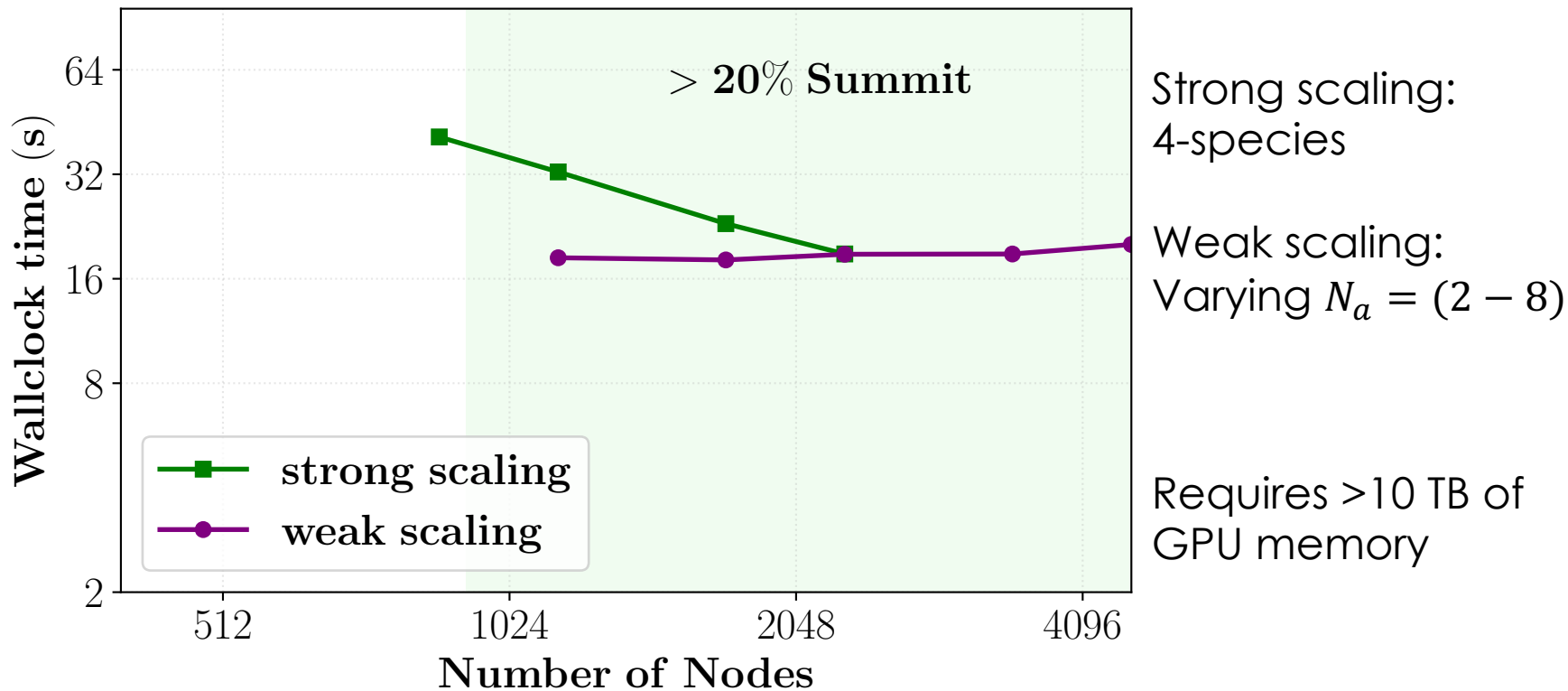
# On GPU systems, high performance cuFFT means short time spent in nonlinear kernel & code is communication-intensive.



Reflects high absolute performance of GPUs rather than poor performance of interconnect

Requires 600 GB of GPU memory

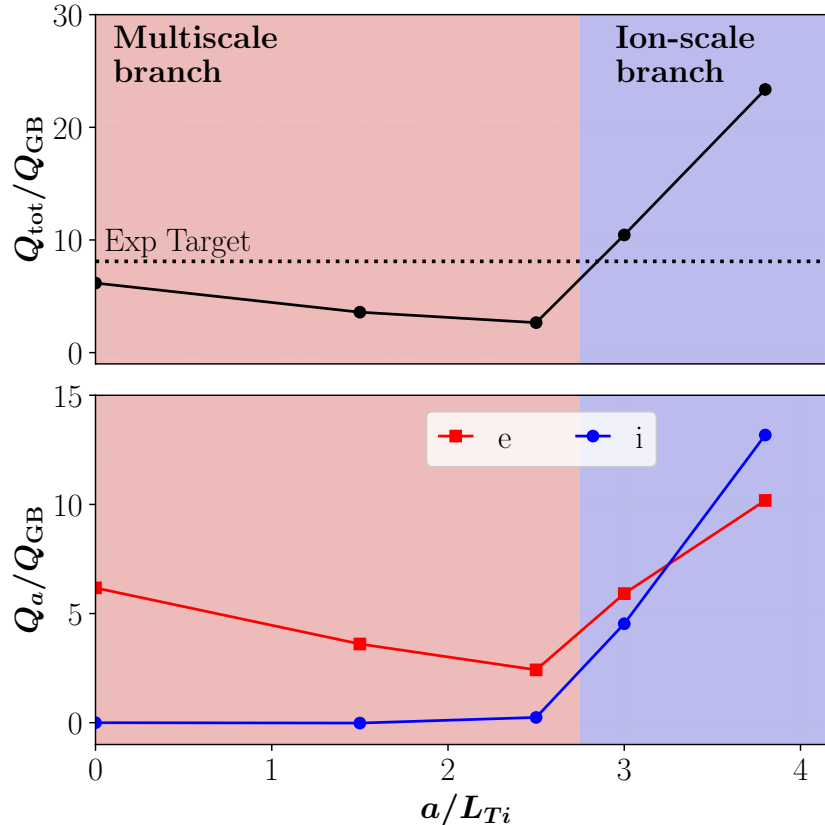
# CGYRO multiscale simulation is well-suited to capability simulation on accelerated systems like Summit/Frontier.





# CGYRO multiscale gyrokinetic turbulence analysis in the tokamak pedestal

DIII-D ITER Baseline H-mode #164988,  $r/a=0.92$

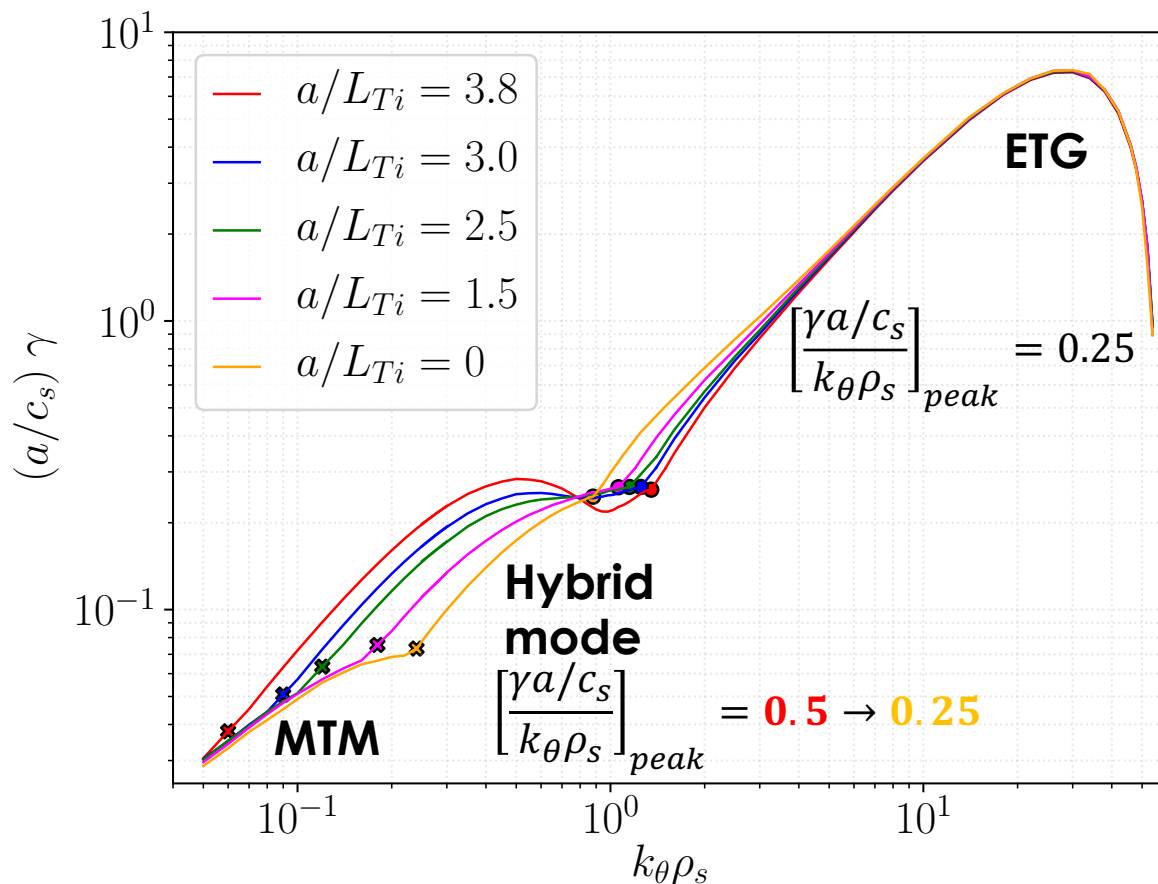


**CGYRO: 250K Summit node-hrs**

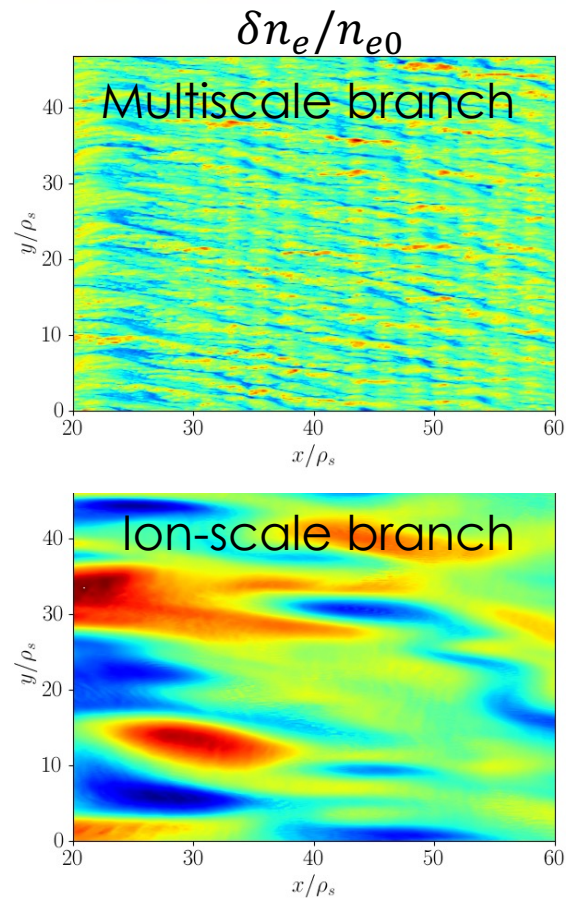
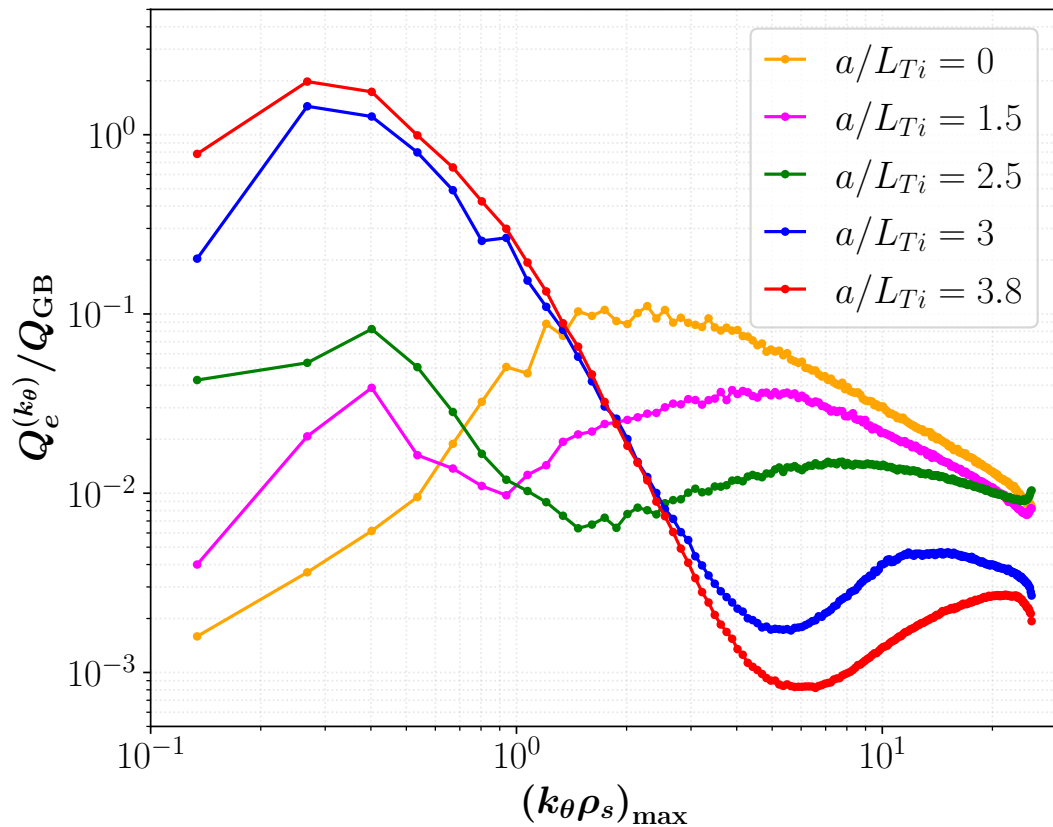
The experiment lies in a **bifurcation region** between **ion-scale-dominated** and **multiscale-dominated** turbulence regimes.

$$\frac{1}{L_{Ti}} = -\frac{d \ln T_i}{dr}$$

# Multiple drift modes are linearly unstable across a broad range of spatial scales from ion-scales to electron-scales.

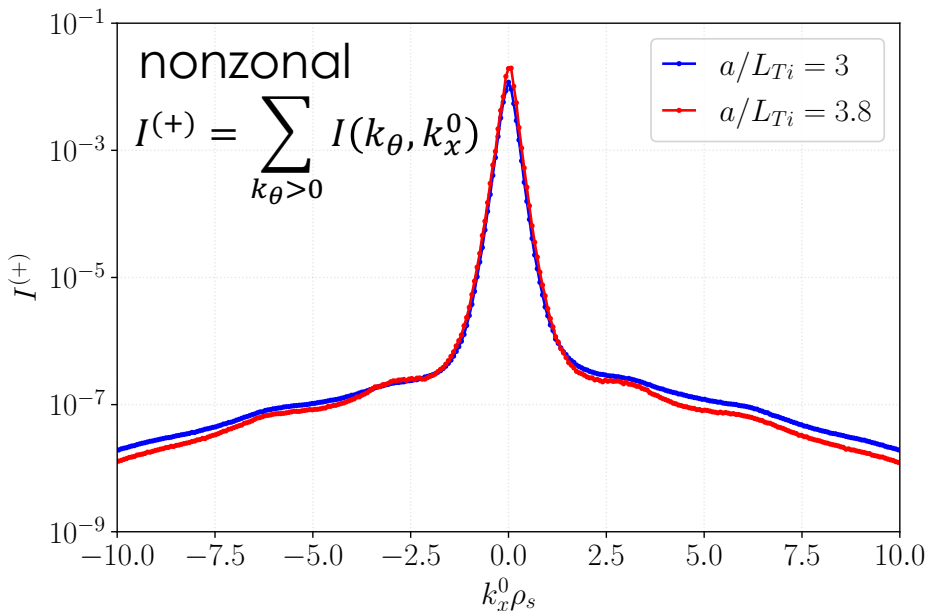


# The electron-scale turbulence is reduced by ion-scale fluctuations through nonlinear mode-mode interaction & an increase in zonal flows.

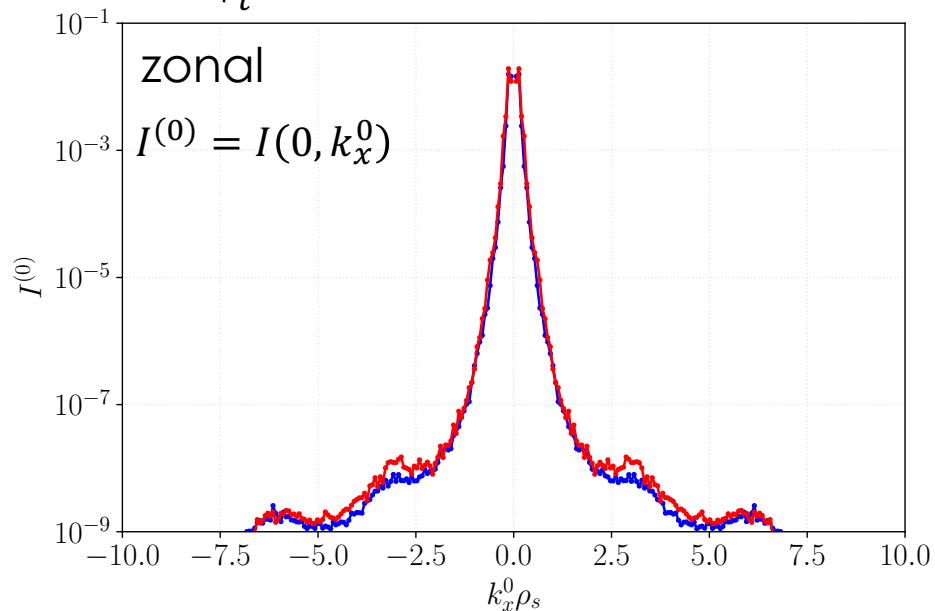


On the ion-scale branch, the fluctuating electrostatic potential intensity is peaked around  $k_x^0=0$  and the total amplitude is large.

$$I(k_\theta, k_x^0) \doteq \left\langle \left| \delta \hat{\phi}(k_\theta, k_x^0) \right|^2 \right\rangle_t$$



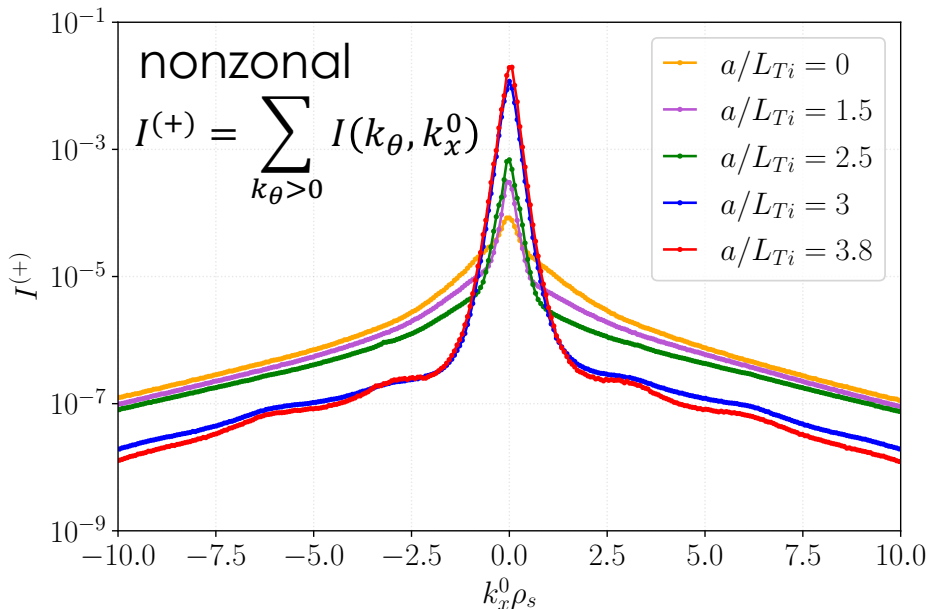
High- $k_x$  nonzonal modes damped by ion FLR.



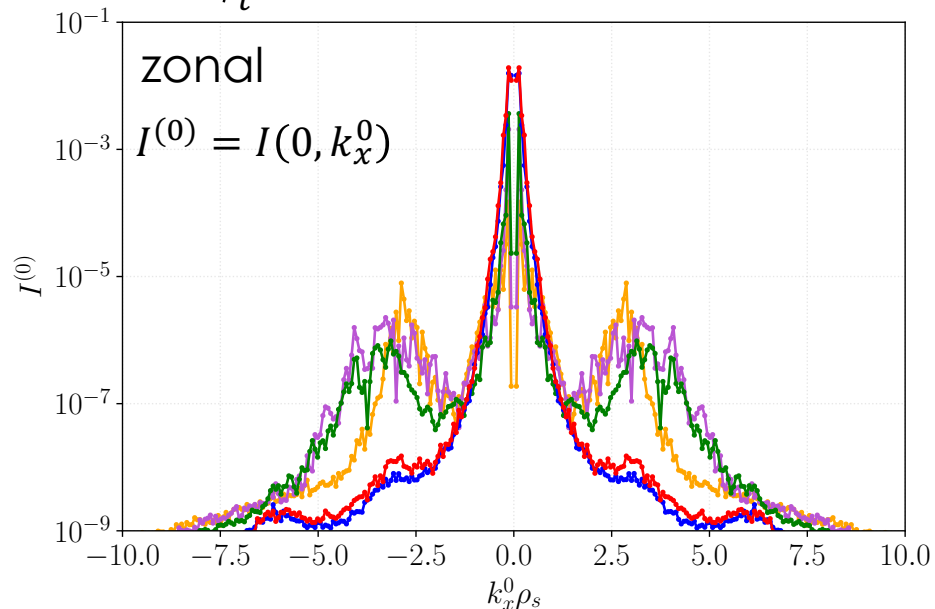
Zf potential is driven by low- $k_\theta$  modes and increases significantly with ion drive.

# Increase in the nonzonal fluctuating intensity is well correlated with increase in the ion energy flux.

$$I(k_\theta, k_x^0) \doteq \left\langle |\delta \hat{\phi}(k_\theta, k_x^0)|^2 \right\rangle_t$$

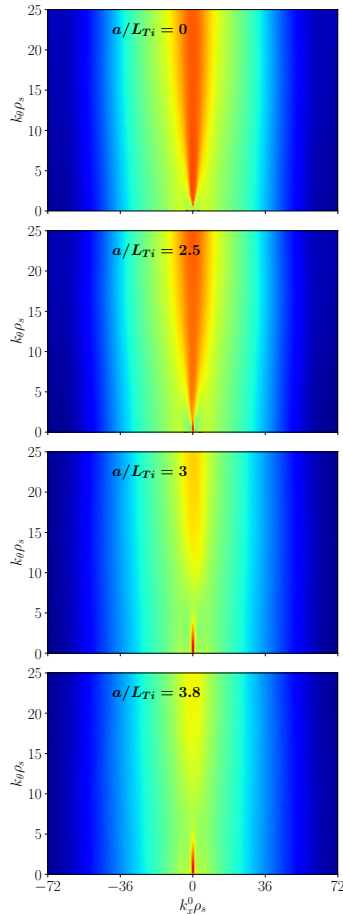


Long wavelength nonzonal fluctuations & low-k-driven zfs play a role in suppressing high-k-ETG turbulence.



ETG-driven zfs give secondary peaking & help to regularize multiscale turbulence.

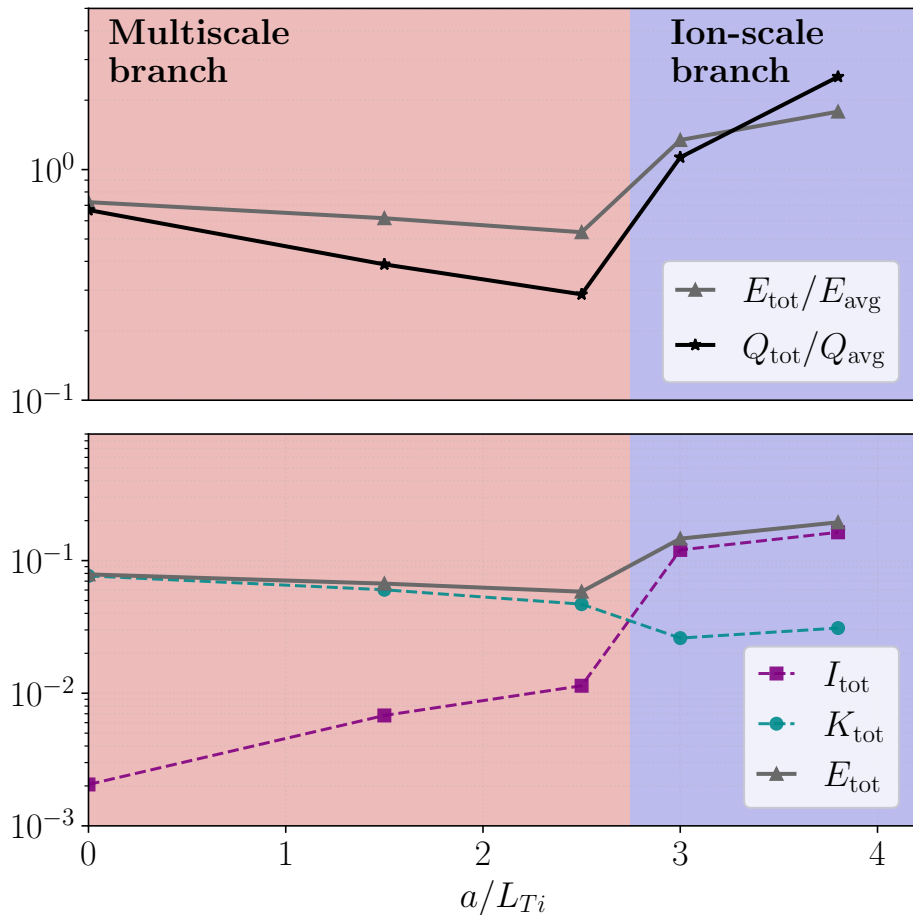
# The drift energy associated with the fluctuating ExB velocity is enhanced for the multiscale branch.



$$K(k_\theta, k_x^0) \doteq k_\perp^2 \rho_s^2 \left\langle |\delta \hat{\phi}(k_\theta, k_x^0)|^2 \right\rangle_t$$

$$\vec{v}_{ExB}(\vec{k}_\perp) = -i \frac{c}{B} \delta \hat{\phi}(\vec{k}_\perp) \vec{k}_\perp \times \vec{b}$$

# In multiscale to ion-scale transition, the energy shifts from dominantly drift kinetic to potential intensity & is correlated with the energy flux.



$$E_{tot} = K_{tot} + I_{tot}$$

Drift energy associated with ExB velocity:

$$K(k_\theta, k_x^0) \doteq k_\perp^2 \rho_s^2 \left\langle |\delta \hat{\phi}(k_\theta, k_x^0)|^2 \right\rangle_t$$

Fluctuating electrostatic potential intensity:

$$I(k_\theta, k_x^0) \doteq \left\langle |\delta \hat{\phi}(k_\theta, k_x^0)|^2 \right\rangle_t$$

# Summary

- A **multiscale-optimized gyrokinetic turbulence solver** (CGYRO) was developed.
  - Uses highly efficient **spectral/pseudospectral** numerical schemes in 4/5 dims
  - Pseudospectral in velocity space gives optimal accuracy of collisions
  - Fully spectral in  $k_{\perp}$  gives spectral gyroaverages  $\rightarrow$  efficiency for multiscale
  - Nonlinear evaluation on GPUs (cuFFT)  $\rightarrow$  maximum performance & scalability
  - Novel conservative upwind scheme in  $\theta$  permits high accuracy EM simulation
  - Spatial discretization and array distribution scheme **targets scalability on next-generation, exascale HPC systems** (GPU-accelerated)
- Optimizations enabled a **first multiscale analysis of pedestal-like transport** with full ion-electron cross-coupling.
  - Experiment lies in bifurcation region btw multiscale-dominated & ion-scale-dominated turbulence regimes. In the transition, electron-scale transport is reduced by nonlinear mixing w/ ion-scale fluctuations & ion-scale-driven zfs.